

*INSTRUCTION MANUAL*  
***MUX 2700 G***  
*MULTIPLEXER*

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## 1. INTRODUCTION

This manual is intended to provide guidance for the installation, operation and maintenance of the Mux2700G HART Signal Multiplexer (HSM) module. To avoid damage, failure or improper operation the contents of this manual should be read and understood before installing and operating the instrument.

The Mux2700G HSM is a compact, plug-in module which is able to accept up to 32 HART channels and to feed them into a single, faster communication line, which is in turn to be connected to a suitable Maintenance Workstation.

The Mux2700G module is intended for use as part of the Elcon HART Interface Solutions (H.I.S.), which provides appropriate interconnection packages for various applications. H.I.S. makes available a wide set of Termination Boards – with or without integrated isolators – to support different applications and to directly interface with the main PLC/DCS equipment. The Mux2700G is simply to be inserted in the selected board to get full HART access to the relevant field devices while preserving the traditional 4/20 mA analogue loop interfaces.

The Mux2700G use the same effective and compact enclosure of the successful HiD series, including the innovative “Quick Lock” mechanism to easily insert/remove the unit from the Termination Board without the need for any tool.

### **Key features summary:**

- low power consumption , very small size;
- compact and proven HiD enclosure, “Quick Lock” capability;
- high noise immunity, industrial-level EMC compliance;
- two DC-blocking capacitors – non-polarised type – on each signal loop;
- optimal mechanical integration with other HiD solutions;
- fully compatible with existing Mux2700 solutions;
- very low loop-interference risk (SIL-3 rating)

### **Warning !**

The Mux2700G unit is not certified for intrinsically safe applications and must not be used to directly interface with hazardous-area located field devices. In fact, some H.I.S. solutions do allow the mounting of the Mux2700G on the same board where intrinsically safe isolators are located. In this case, the safety-related application areas must be addressed by trained personnel which is fully acquainted with the principles of intrinsically safe system. Elcon Instruments has published a complete tutorial entitled “Guide to Intrinsic Safety” covering most aspect of intrinsic safety. The book can be obtained from Elcon Instruments free of charge.

## 2. UNPACKING AND STORAGE

Upon receipt of the materials, you should immediately check the integrity of both packaging and contents. In case of damage due to shipping, the receiver should promptly and properly report to the shipper supplying all necessary information.

If the instruments are not for immediate use, a check is recommended about the compliance of the units specifications (as indicated on the label) with both order specifications and with the actual application requirements.

In case of storage of instruments and accessories, proper care should be taken to protect them from any possible damage. Always store instruments in their sealed original packaging until they are installed. In addition, adequate protection should be provided from:

- humidity and temperature excursions outside the specified range;
- aggressive or polluting atmospheres (e.g. SO<sub>2</sub>, H<sub>2</sub>S, mists, salts, smokes, dusts);
- access by insects/rodents that could damage packaging or content;
- mechanical shocks or intense vibrations.

### 3. FUNCTIONAL DESCRIPTION

#### 3.1 Overview

The Mux2700G HART Signal Multiplexer (HSM) provides 32 signal channels for connection to field located, "smart" transmitters or control devices supporting digital communication according to the HART standard. The Mux2700G acts as a gateway between a Maintenance Workstation (MW) – typically a PC with suitable SW – and the field instrumentation. The MW connects, in a multi-point configuration, with up to 31 Mux2700G using a fast RS-485 communication channel.

The HART protocol is a widely accepted technique by which standard 4/20 mA field devices can support digital communication for configuration and maintenance purposes. A modulated, audio-frequency signal (Bell202 FSK) is in fact superimposed to the analogue current loop providing a 1200 baud, half-duplex communication capability. The HART protocol, being a widely accepted standard specified up to the application layer, permits an effective integration, at the Maintenance Workstation level, of field devices from different manufacturers.

The Mux2700G HSM not only uses the HART protocol to communicate with the field devices but also to interface with the Maintenance Workstation via an RS-485 link. In this way, an highly standardised solution is obtained.

Under the supervision of the Maintenance Workstation, the Mux2700G interrogates each field device, retrieving information which are then stored in an internal data-base. This internal data-base can then be accessed in real-time by the MW which however, when required, can also directly communicate with any specific field device.

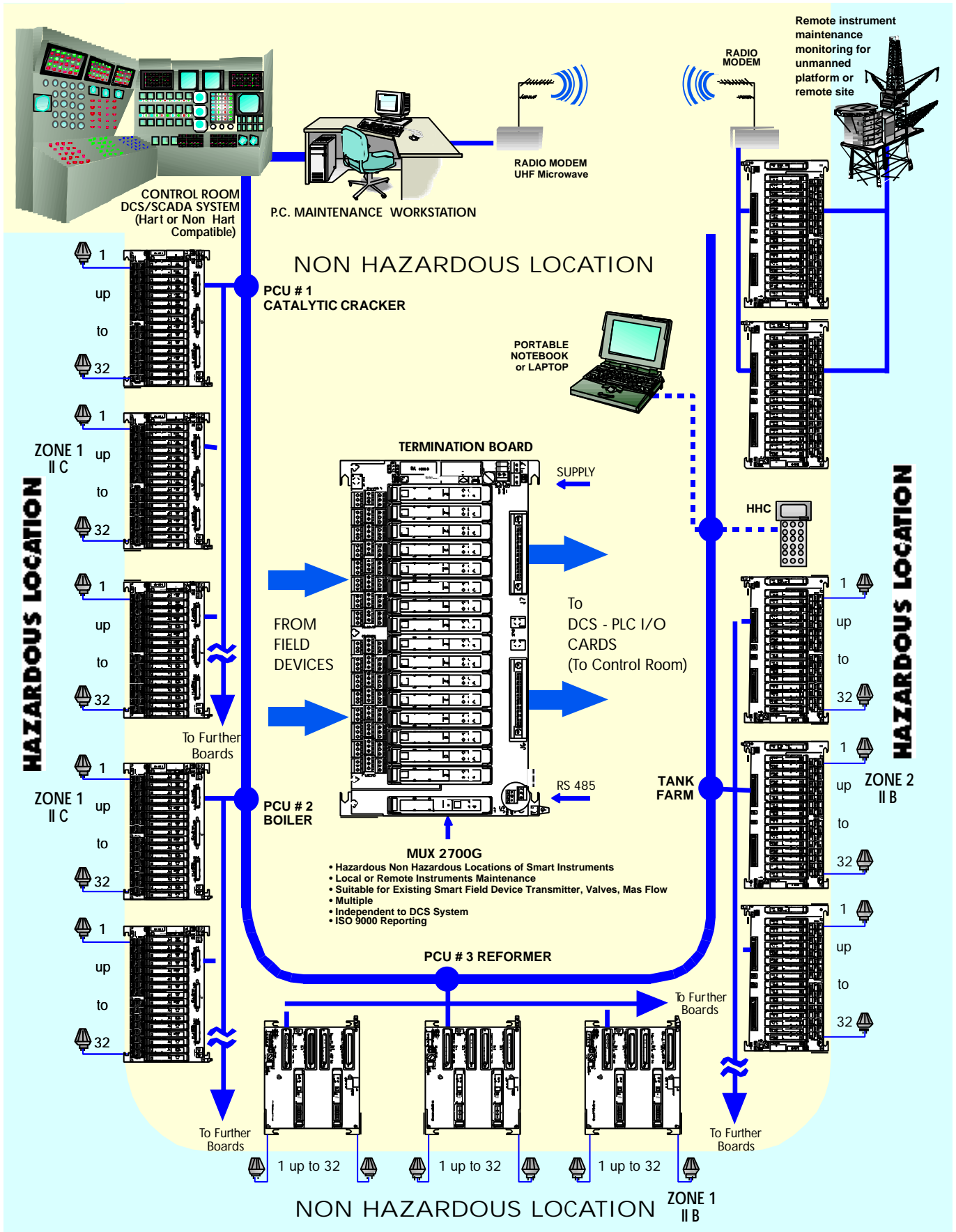


Fig. 1

### 3.2 Operation

The Mux2700G HSM module implements HART protocol commands and acts as a gateway device between the Maintenance Workstation (MW) and the field devices. It responds to commands received from the MW (RS-485 interface) as a slave device and issues commands to the HART slaves (field channels) acting as either a Primary or Secondary Master (according to the HART specification).

A modified version of the HART protocol was implemented on the RS-485 physical layer to obtain a fast and reliable communication with the Maintenance Workstation. In this way, standard HART messages can be used by the MW for an effective, seamless integration of field devices from different manufacturers.

The Mux2700G can continuously poll each connected field device to get the specified primary (or secondary) HART variable, automatically updating the internal data-base. This is called **scan** operation, and can be enabled or disabled by the Maintenance Workstation (the Mux are factory set in the "Scan-Off" condition). When in the "Scan-On" mode, the MW can generate a warning message whenever a field device stop communicating (e.g. because it is disconnected from the loop).

At power-up, the Mux2700G always performs a **locate** activity, that is to say, it polls all the 32 channels to find any connected – and communicating – field device and to rebuild the required, internal access tables. The locate activity can be started also by the Maintenance Workstation, and this is usually required to be able to communicate with a new field device connected to the Mux after power-up. The locate time can range from 15 to 60 seconds, depending on the specified retry counts (the Mux are factory set with a retry count = 3, resulting in around one minute of locate time).

In addition to providing access to the HART-capable field instruments, the Mux2700G module is itself, in all respect, an HART device with parameters and internal functions available to the user (e.g. Tag, Description and unique DIN – Device Identification Number).

### 3.3 LED indications

The information provided by the Mux2700G LED (mounted at the panel front) is summarised in the following table:

Colour	Name	Function
Yellow	HART TX	ongoing HART communication with field devices
Green	PWR ON	supply indicator (can blink at power-up)
Red	FAULT	internal fault indication (power-up detection only)

### 3.4 Power-up sequence

In the following, the normal Mux2700G power-up sequence is described. This is always the standard power-up behaviour, unless SW8 (at the panel front) is set into the Test position.

- Immediately after power-up, the 3 LEDs goes immediately On, and remains in this state for around 3 seconds.
- An internal **self-test** is then performed and, if any problem is detected, the Red LED goes fixed On. (during the self-test - which lasts around 8 seconds - the Green LED keeps blinking).
- The Yellow LED then start blinking, indicating that the Mux2700G is performing the **locate** activity, that can last up to around one minute.
- The Yellow LED should then go Off, unless the **scan** operation is enabled or the Maintenance Workstation is directly communicating with a field device.

### 3.5 Application guidelines

The Mux2700G HSM is not normally intended to be designed by the user in a specific application, but to be used as part of the Elcon HART Interface Solutions (H.I.S.) offering, which provides appropriate interconnection packages for a wide range of applications, as well as a set of compatible Maintenance Workstation solutions. This makes the Mux2700G application straightforward, because most “tricky” interface and compatibility issues have already been solved, and a ready to use, plug-and-play solution can be provided.

As an example, when “HART filters” are required to ensure the compatibility with a specific PLC/DCS, these are usually directly integrated at the H.I.S. level.

However, there can be situations, as with “general-purpose”, screw-terminals H.I.S. boards, in which some care in wiring and installation is required to set-up a working system. An overview of some H.I.S. solutions is presented in section 4., please also refer to the relevant H.I.S. documentation for more information.

As a general guideline, it is worth noting that the Mux2700G input channels must be connected across the 4/20 mA loop in such a way as to see parallel resistance not lower than 200 (250 recommended). If this is not the case, the available HART signal could be too weak to guarantee a reliable communication. A problem of this type can be found with an analogue-input card with a low internal current-sense resistor, or with any loop-connected device that, in spite of having an high DC resistance, presents too low an impedance on the 4/20 mA loop at HART frequencies (1200 / 2200 Hz).

In addition, it is always recommended to connect the “+” input terminal at higher DC voltage level with respect to the “-” input terminal (that will be in many cases at a GND level).

### 3.6 Hardware architecture

The heart of the Mux2700G HSM module is the microprocessor (CPU). One CPU serial port – together with the HART modem and the related analogue circuits – implements the physical layer of the HART protocol. A second CPU serial port is used to drive the opto-isolated RS-485 interface.

The internal architecture of the Mux2700G Multiplexer is depicted in the following block diagram of Fig. 2. As you can see, the HART modem is multiplexed on the 32 available field channels to get a cost-effective and compact solution.

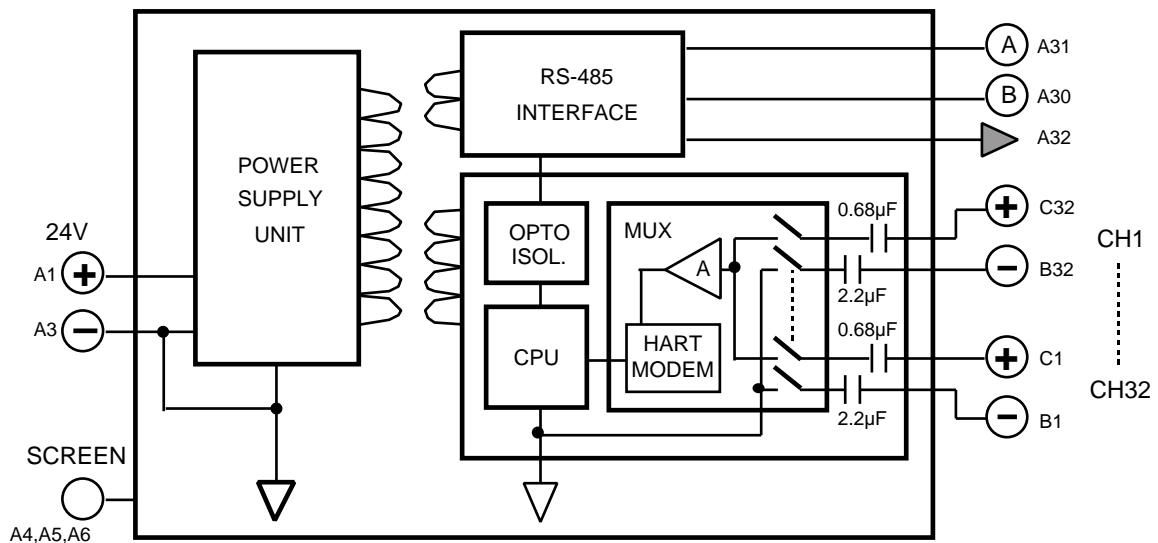


FIG. 2

A full three-port isolation is also provided. The power supply section is in fact galvanically isolated from both the analogue multiplexing section and from the RS-485 serial line.

Each input channel is also DC-isolated from the input GND by two non-polarised capacitors. The dual capacitor solution, usually not to be found on comparable products, avoid the need of having a single common ground for all input signals. In this way, it is also possible to connect to any “floating” loop without any loss of isolation

In general, the three-port isolation combined with the dual-capacitor approach result in an effective and reliable solution, with such advantages as:

- undesired ground loops can be easily avoided;
- existing isolation between different ports can be preserved;
- very low risk of disturbing the 4/20 mA loop signal, also in case of fault.

In fact, the Mux2700G architecture is such that any internal single fault never result in any interference with an input connected 4/20 mA loop. For this reason, the Mux2700G can be used as a monitoring device within safety-sensitive applications.

### **3.7 Software architecture**

The Mux2700G HSM is not normally intended to be designed by the user in a specific application, but to be used as part of the Elcon HART Interface Solutions (H.I.S.) offering, which includes a set of compatible Maintenance Workstation solutions.

This means that the user doesn't have to worry about either the internal details of the unit software functions nor about the specific RS-485 protocol features. In fact, the Maintenance Workstation software make most of these details “invisible” to user by providing an user-friendly, graphical man-machine interface.

When you have any special need or problem, please contact Elcon for additional information.

## 4. HART INTERFACE SOLUTIONS OVERVIEW

### 4.1 Presentation

HART Interface Solutions (H.I.S.) makes available a wide set of Termination Boards to support different applications. There are several styles of interconnection methods available for mounting of the Mux2700G to suit the various demands of particular installations. These satisfy the basic requirements of:

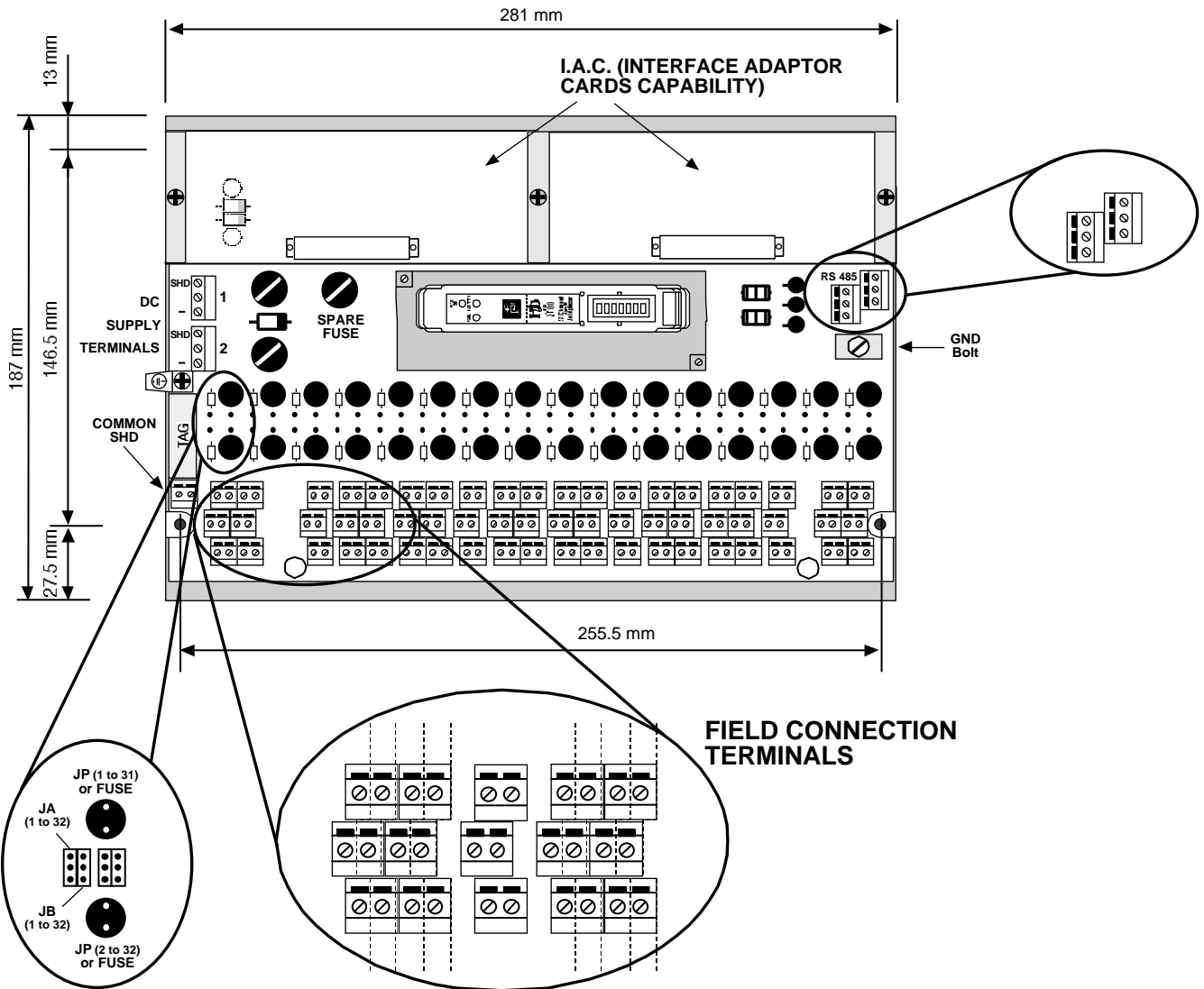
- general purpose wiring interconnection;
- replacing the function of existing control system termination panels;
- including Intrinsic Safety isolating interfaces.

The details of specific applications can be found in the support documentation for the HART Interface Solutions (H.I.S.) panels which are custom designed to satisfy these particular needs.

However, the following sections give details of three generic solutions for the mounting of the Mux2700G which are included to show the scope of these possibilities:

- single Mux2700G mounting on termination panel: 1132/CON-8-H-DS
- multiple Mux2700G mounting on termination panel: 2108/64-HART-D
- Mux2700G integrated with HiD 2000 IS interfaces: 2116/HAT/SACON-HART

## 4.2 1132/CON solution



### Selecting Different Input Connections Arrangements

**1) LOOP SUPPLY TRANSMITTERS (non individually fused inputs)**

- Install jumper JP
- Install jumper JPA and JPB on position 3
- Connect Tx at terminals +24V (positive) and C (negative)
- For individually fused loop supply Tx plug TR5 50mA value fuses in place of JP jumpers (connections remains the same)

**2) 1-5V FROM FIELD**

- Install JPA and JPB on position 1
- Connect inputs at terminals C (positive) and B (negative)

**3) 4-20mA FROM FIELD**

- Install JPA on position 3
- Install JPB on position 1
- Connect 4-20mA inputs at terminals C (positive) and B (negative)

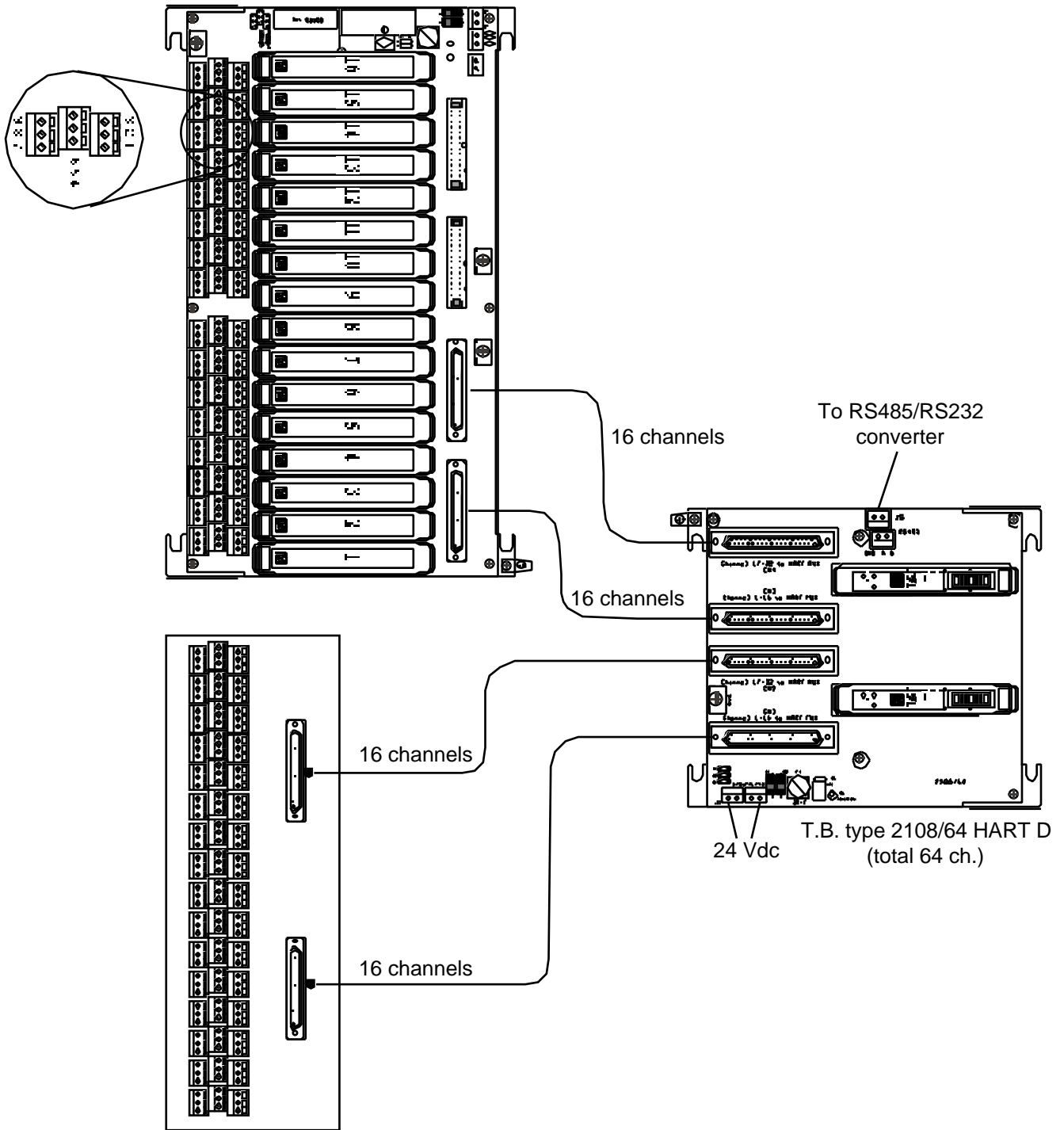
**4) I/P SMART**

- Install JPA on position 1
- Install JPB on position 1
- Connect I/P at terminal C (positive) and B (negative)

**Fig. 3**

### 4.3 2108/64 HART D solution

Elcon I.S. Termination Panel  
with pick-off for HART signals (example)



General purpose  
1-5 V HART signal inputs  
(PHOENIX VARIOFACE style)

FIG. 4

### 4.4 I.S. Integrated solutions (Mux2700G with HiD2000 Intrinsic Safety interfaces)

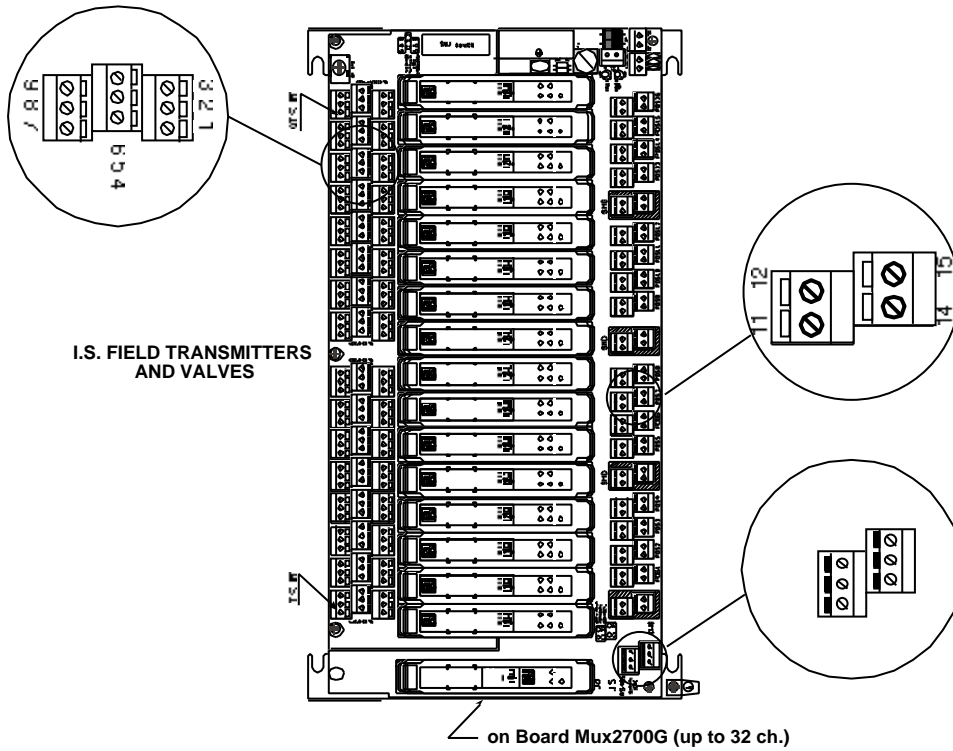


FIG. 5A

### LOOP DIAGRAM (Example of an I.S. integrated solution)

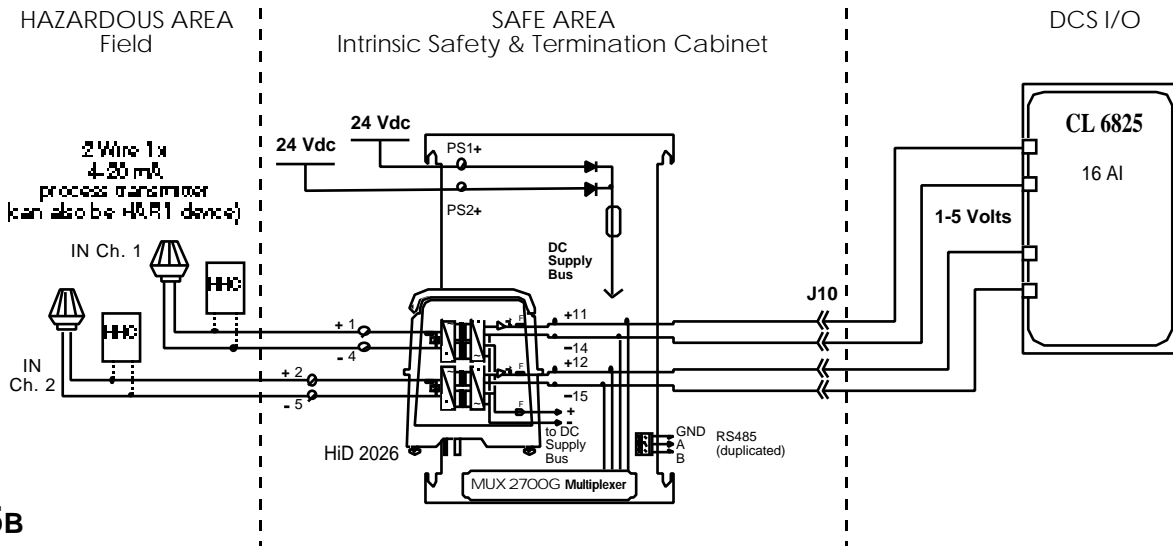


FIG. 5B

### 4.5 Electrical connections

All H.I.S. electrical connections and wiring should comply with the standards and installation rules (e.g. ISA RP12.6) applicable in the country of use.

Before powering the Termination Board, verify the polarity and the voltage level of the supply line. The supply voltage must be within the limits specified for the Mux2700G module.

**Warning !**

Improper supply connections could seriously damage the Mux2700G module.

## 5. MAINTENANCE WORKSTATION OVERVIEW

### 5.1 General

A Maintenance Workstation (MW) is to be connected to the installed multiplexers to implement the required, HART-related configuration and supervision activities. In fact, the Mux2700G basically acts as a gateway between the field devices and the MW.

The Maintenance Workstation is typically made of a suitable software package loaded on a standard desktop PC equipped within external RS-232/RS-485 converter. The recommended operating system is Windows NT, but Windows98/95 is also generally supported. As for required PC features, please refer to the documentation of the applicable MW software package.

At least one free serial communication line (RS-232) must be available on the Maintenance Workstation to connect the 232/485 converter. Most MW software packages generally permit the usage of more than one serial line (with additional 232/485 converters) to increase the total number of accessible field devices.

Up to 31 Mux2700G modules can be connected to a single RS-485 serial line, for a total of 992 accessible field devices. The Maintenance Workstation is usually able to support more serial lines, so it is possible to effectively manage a few thousands of field devices without problems.

The recommended RS-232/RS-485 converter is the MD44 model (Westermo). Other equivalent devices can be found on the market (e.g. from Keithley) but it is better to check their compatibility with the specific Maintenance Workstation software.

### 5.2 Software packages

Several PC software packages are available which include support for the Elcon Mux2700G HSM.

Asset Management Solutions (**AMS**) from Fisher Rosemount, ([www.frco.com/fr/solutions/ams](http://www.frco.com/fr/solutions/ams)) is a scalable software product with full HART abilities, and functionality can be added as required. The "engine" of AMS is the Field Server which provides access to HART information from any device with a common user interface and supports a common database. The Universal System Interface is the software driver for an online link from the Field Server to the Elcon Mux2700G. Additional "snap-on" application packages are available for configuration, calibration, maintenance, valve diagnostics etc. to suit customer needs.

**Valvelink** from Fisher Controls ([www.fisher.com](http://www.fisher.com)) provides an easy-to-use environment for configuring, calibrating and diagnosing the operating characteristics of Fisher Fieldview instruments such as valve controllers and transducers.

Applied System Technologies **Cornerstone** family of products is a comprehensive package useful for commissioning, calibration and maintenance management of industrial instruments both in the lab and in the field. Cornerstone products provide multi-vendor support for all types of HART compatible smart instruments. Cornerstone creates and maintains a comprehensive instrument database and individual histories of the configuration, test, calibration and maintenance activities performed on each instrument.

Finally, **Field Browser** from Neles/Metso Automation is another package which can directly interface with the Elcon Mux2700G HSM.

For details about these software packages please refer directly to the supplier mentioned.

## 6. Mux2700G SPECIFICATIONS

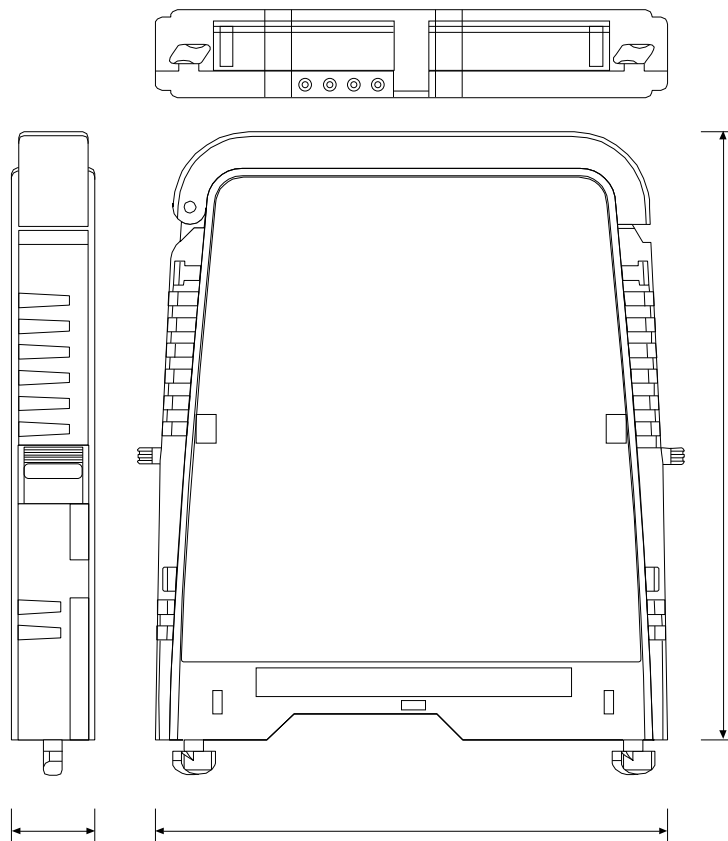
N.B.: all values are typical unless otherwise specified.

### 6.1 General

Operating Temperature:	0 to 55 °C (32 to 131 °F)
Storage temperature:	-20 to 70 °C (-4 to 158 °F)
Relative humidity (non condensing):	5 to 90 %
EMC:	EN50081-2, EN50082-2
Isolation ( <i>Supply</i> port to <i>Signal</i> port): Isolation ( <i>Supply</i> port to <i>Serial</i> port): Isolation ( <i>Serial</i> port to <i>Signal</i> port):	1400 Vac, rms 1400 Vac, rms 500 Vac, rms
CE marking	carried

### 6.2 Mechanical

Dimensions:	see drawing
Case:	HiD style, Polycarbonate
Mounting:	plug-in on Termination Board (no tool required)
Protection class:	IP30
Connectors:	2, plug-in, 40-poles miniature connectors
Hot-plug in:	supported
Unit weight:	about 140 grams



### 6.3 Supply port

Supply voltage:	24 Vdc (-15%, +25%)
Supply current:	20 Vdc 32 mA (typical, RS485 quiescent)
	24 Vdc 28 mA (typical, RS485 quiescent)
	30 Vdc 23 mA (typical, RS485 quiescent)
Protection:	internal fuse, not user-serviceable

### 6.4 Signal port (HART)

Channel number:	32 signal loops
DC-isolation:	dual-capacitor isolation on each loop
Allowed common mode voltage:	up to 30V
Differential mode clamping:	+/- 5.2V (for transient or AC signals)
Receive signal range:	0.12 Vpp < signal < 1,5 Vpp
Receive impedance magnitude:	> 5000
Carrier Detect levels:	signal > 0.12 Vpp — CD asserted
	signal < 0.080 Vpp — CD not asserted
Transmit signal amplitude :	200 mV (200 load, typical) 500 mV (500 load, typical)
	200 load — 150 mV < signal < 250 mV
Carrier stop time	< 10 bit time
Device connection type:	DC-isolated bus device
Impedance level type:	High Impedance device
Data link type:	Primary or Secondary Master (configurable)
Field multi-drop support:	available on request

For additional, more detailed HART-related specifications, please refer to the *HART FSK Physical Layer Specification Rev.8.0* available from the HART Communication Foundation (HCF\_SPEC-54), which the Mux2700G module is generally compliant with.

#### Notes :

- To minimise input capacitors size and to get an higher output signal level, the Hart signal transmit section is based on a current generation technique. For this reasons, the output signal level is proportional to the external load, which should not exceed 500 to avoid possible cross-talk or saturation problems.
- The specified transmit-signal amplitude is a DC value measured at the centre of a waveform semi-period.
- To maximise allowed cable length and to avoid noise problems, you should avoid to connect to the MUX HART low impedance devices < 250 .

### 6.5 Serial port (RS-485)

Line type:	RS-485, differential pair plus GND
Line speed:	9600 Baud, 19200 or 38400 Baud
Line topology:	multi-point, master-slave connection
Device type:	slave (up to 31 slave Mux can connected to a single master)
Slave addressing range:	1 to 31 (0 reserved)
Protocol type:	H-Port (HART based)
Master device:	Maintenance Workstation (MW)

#### Warning !

A suitable RS-232 to RS-485 converter is required to connect the port with a standard PC (see Fig. 6). As for RS-485 line detailed specifications, please refer to the relevant standard.

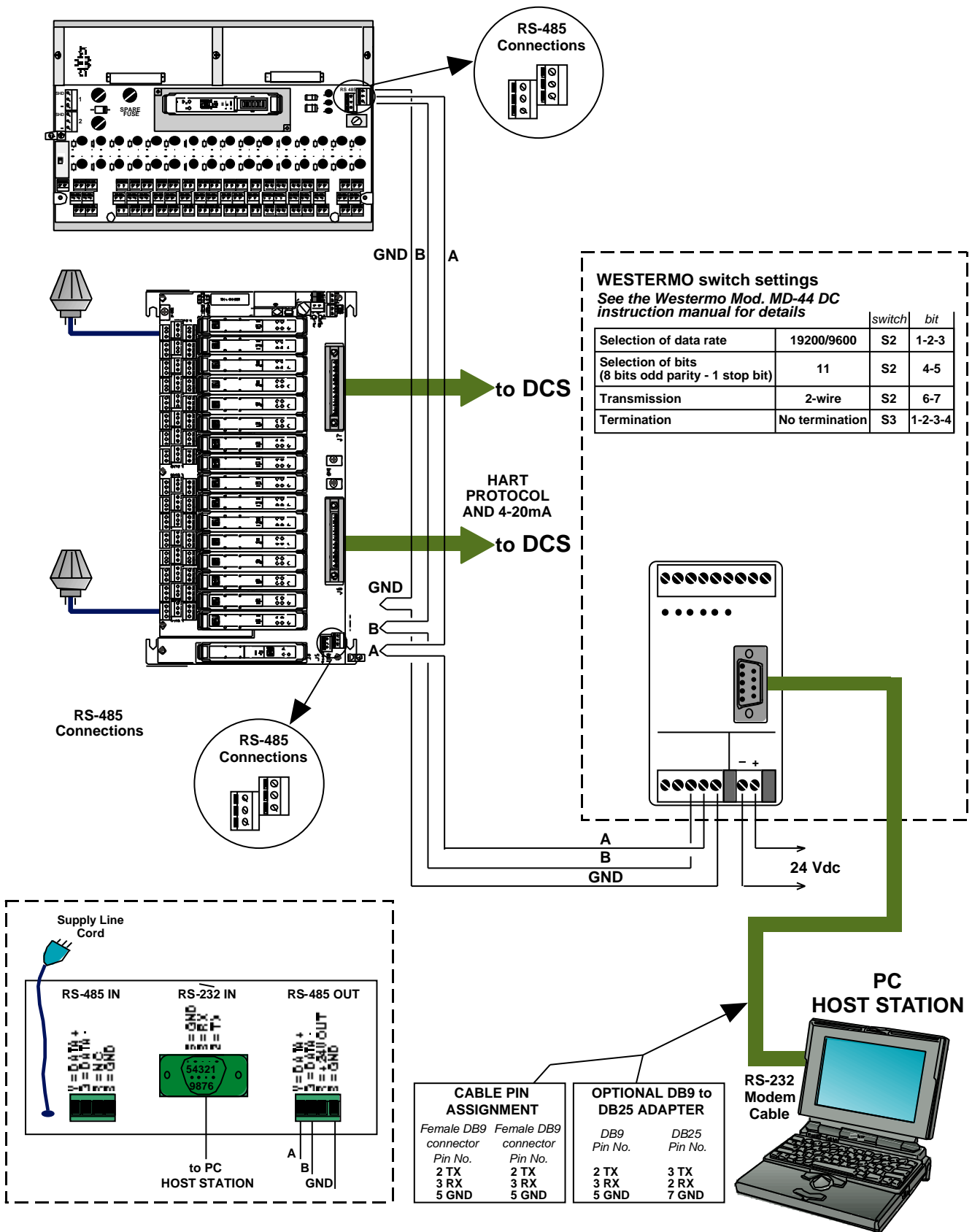


FIG. 6

## 7. INSTALLATION AND CONFIGURATION

### 7.1 Operating environment

The Mux2700G HART Signal Multiplexer module rate on wide temperature and humidity ranges. It is however desirable to limit the environmental stress, so to maximise the expected life time. It is therefore recommended not to operate the unit near the specified high-temperature limit for long periods of time.

In addition, you should remember that high humidity (above 60%), when in conjunction with corrosive atmosphere and/or temperature stresses, can result in corrosion, with bad effects on connectors contact quality.

The Mux2700G HSM was carefully tested according to the specified EMC (electromagnetic compatibility) standards. The verifications were either carried out by certified test houses or internally by using equivalent test set-ups. Comprehensive reports were always used to register test results.

The compliance with the relevant standards is not however such to always guarantee the proper unit behaviour regardless of the operating environment and of the specific system configuration. The following guidelines are useful to minimise this type of risk:

- all system units should carry the CE mark and comply with the related EMC standards;
- when a strong RF noise is expected, use screened and properly grounded I/O cables;
- don't run I/O cables side by side with potentially noisy system wiring;
- avoid ground loops as much as possible and use proper grounding and earthing techniques.

### 7.2 DIP-switch configuration

The configuration DIP switches located at the top of the unit as shown in the following drawing. (Fig. 7a-7b and the address setting tables at page 18).

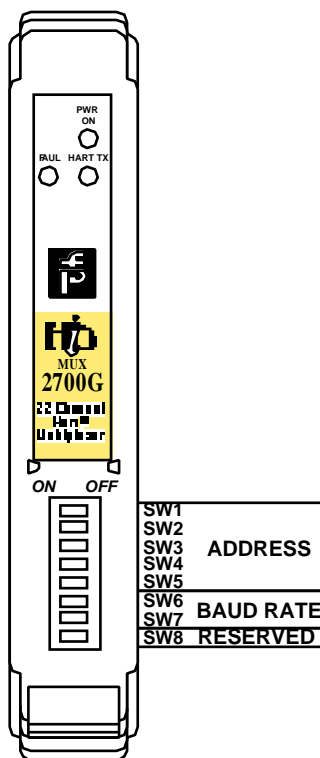


FIG. 7A

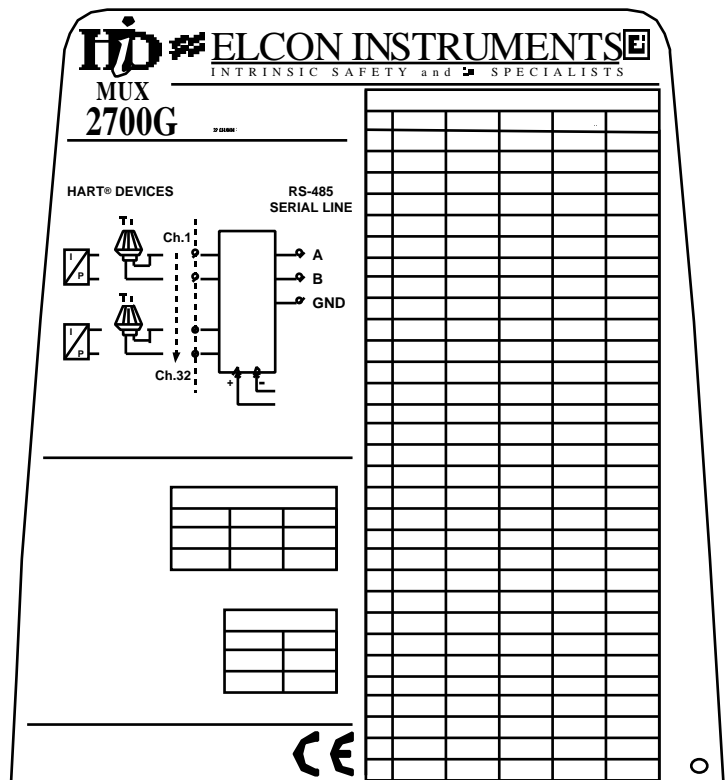


FIG. 7B

• **Address setting**

The Mux2700G module operates as a slave device on a multi-point RS-485 serial line. A unique address is therefore to be specified for each Mux connected to the same serial line. To set the required address, use the first five switches according to the following table. Please note that the address 0 is reserved and is never to be used.

RS-485 ADDRESS					
	SW1	SW2	SW3	SW4	SW5
0	OFF	OFF	OFF	OFF	OFF
1	ON	OFF	OFF	OFF	OFF
2	OFF	ON	OFF	OFF	OFF
3	ON	ON	OFF	OFF	OFF
4	OFF	OFF	ON	OFF	OFF
5	ON	OFF	ON	OFF	OFF
6	OFF	ON	ON	OFF	OFF
7	ON	ON	ON	OFF	OFF
8	OFF	OFF	OFF	ON	OFF
9	ON	OFF	OFF	ON	OFF
10	OFF	ON	OFF	ON	OFF
11	ON	ON	OFF	ON	OFF
12	OFF	OFF	ON	ON	OFF
13	ON	OFF	ON	ON	OFF
14	OFF	ON	ON	ON	OFF
15	ON	ON	ON	ON	OFF
16	OFF	OFF	OFF	OFF	ON
17	ON	OFF	OFF	OFF	ON
18	OFF	ON	OFF	OFF	ON
19	ON	ON	OFF	OFF	ON
20	OFF	OFF	ON	OFF	ON
21	ON	OFF	ON	OFF	ON
22	OFF	ON	ON	OFF	ON
23	ON	ON	ON	OFF	ON
24	OFF	OFF	OFF	ON	ON
25	ON	OFF	OFF	ON	ON
26	OFF	ON	OFF	ON	ON
27	ON	ON	OFF	ON	ON
28	OFF	OFF	ON	ON	ON
29	ON	OFF	ON	ON	ON
30	OFF	ON	ON	ON	ON
31	ON	ON	ON	ON	ON

• **Baud-rate setting**

The next two switches permit to set the desired serial line baud-rate. The same baud-rate must be set also on the RS-232/RS-485 converter and on the PC RS-232 serial line. Please note that the remaining SW6/7 configurations are reserved and never to be used.

RS 485 BAUD RATE		
	SW6	SW7
9600	OFF	OFF
19200	ON	OFF
38400	OFF	ON

• **SW8 setting**

The SW8 switch must be always set to OFF and its reserved for factory-test usage.

### 7.3 Connections and mounting

The Mux2700G HSM module is a plug-in unit intended for insertion in a suitable H.I.S. Termination Board. Therefore, the primary electrical connections (supply, field connection, serial lines) are made at the Termination Board level. Please refer to the relevant board instruction manual for details.

The Mux2700G box – unlike other HiD-type enclosures – is not mechanically polarised because its different connectors avoid the possibility of wrongly inserting it in an isolator slot. No polarisation prong is therefore to be found on the bottom of the enclosure.

To mount a new Mux2700G module on the board, proceeds as follow:

- identify the right Mux2700G slot by consulting the relevant documentation;
- carefully align the unit connectors with the board ones, then gently press down module;
- push down the yellow tabs on each side of the module to firmly secure it to the panel.

To remove an installed Mux2700G, simply lift the yellow tabs and gently unplug from the panel.

The Mux2700G Multiplexer is an hot plug-in capable module therefore, when required, you can mount it without disconnecting the power from the relevant Termination Board. At plug-in time, no relevant disturbance is to be expected on 4/20 mA field signals. Before powering up the unit for the first time, please remember to carefully check supply voltage level and polarity.

When required, “tag labels” are available to be inserted on the transparent lid located at the top of the module. This could be useful for general identification purposes.

### 7.4 Final checks

Before applying power and putting the Mux2700G module into operation, carefully check the following:

- **On termination board**
  - supply connections, voltage level and polarity
  - field wiring polarity and tags
  - serial line (RS-485) wiring, with special care to polarity
- **On Mux2700G module**
  - RS-485 address (between 1 and 31)
  - RS-485 baud rate (9600,19200 or 38400)
  - SW8 position, (OFF)
- **On RS-232/RS-485 converter**
  - baud rate (9600,19200 or 38400)
  - RS-485 connections, with special care to polarity
  - RS-232 and supply connections
- **On Maintenance Workstation:**
  - proper software installation and configuration
  - baud rate (9600, 19200 or 38400).
  - RS-232 line operation and connections

**Warning !**

Please remember that – unless the GND signals at both ends are connected to earth – the RS-485 communication line needs three wires (differential pair plus GND). It is not recommended to use the cable shield as GND connection (i.e. third wire).

**Warning !**

Improper supply connections could seriously damage the unit.

**RS-485 note:**

According to the RS-485 standard you can connected up to 32 devices to a single line of up to 1200 meters (when your data rate is lower than 100K baud). To get a reliable connection we recommend not to exceed this limits. You should also verify that the connection cable is compliant with the standard specified requirements (but at low data-rates you don't generally have any problem). Finally, don't forget that for an RS-485 line a suitable termination resistor is required at both ends, and you should switch it On both on the RS232/RS485 converter and on the farthest Termination Board panel (i.e. on the last device on the RS-485 bus).

## 8. MAINTENANCE AND TROUBLESHOOTING

### 8.1 Maintenance

No periodic maintenance or calibration is required for this product, which is also not intended for direct repair from the end-user. For these reasons, the Mux2700G enclosure was not designed to be easily opened (and a special tool is in fact required at this purpose).

#### **Warning !**

Any attempt to open the unit or to directly repair it will make the warranty null and void.

### 8.2 Power-up self-test procedure

This the first recommended check when there is any doubt about proper Mux2700G operation.

- When the Mux2700G is powered, the three LEDs should light for about 3 seconds. If, after this time the red LED remains fixed in the On status, the unit should be returned to Elcon for repair.

### 8.3 Additional troubleshooting

When the unit pass the power-up self-test and there are still operational problems, try the following checks:

- Verify the power-up sequence – as described in section 3.4 – to get more information about the situation.
- Repeat the checks described in section 7.4 to identify possible problems.
- When you have signal level problems, verify that the equivalent, parallel network resistance is at least 200  $\Omega$  (250  $\Omega$  recommended) as required by the Hart specifications.
- When the communication with the Maintenance Workstation is OK but you can not communicate with the field devices, check with an oscilloscope the Hart signal level and noise content on the loops.
- With a relevant noise present at the Hart signal level – and when it is not viable to reduce it in any other way – you can consider the increase of the loop series resistance up to 500  $\Omega$  (when compatible with the DC 4/20 mA loop requirements). In this way, the Hart signal level double, as well as the signal-to-noise ratio

#### **Note:**

Elcon technical support is available to advise about special problems or unclear situations. Please always contact Elcon before returning any suspected defective unit, either in warranty or not.

## 9. QUALITY MANAGEMENT POLICY

The Elcon mission is to guarantee the highest standards of Quality for the products and services offered and in Elcon “Quality” means to keep up with customer expectations and to assure the customers’ satisfaction. In practice, the products must conform with specifications, defects must be prevented and the costs due to non conformance must be reduced.

In order to achieve these targets Elcon has enlarged the concept of “Customer” and introduced the concept of Company internal Customer. In this way all those persons that within the Company benefit from other people’s work or service are considered as if they are the Customer Elcon considers **Total Quality** as one of the fundamental factors in achieving its mission. At Elcon the two key elements of Total Quality are “Quality System and “Continuous Improvement”.

The Elcon **Quality Assurance System** is the set of organisational structure, responsibilities, procedures, processes and resources for implementing Quality management. Elcon has adopted the standard EN ISO 9001 as reference for its own Quality System. In accordance with this choice our key suppliers also have to comply with a Quality System conforming to the EN ISO 9000 standard.

This Quality System guarantees confidence in Elcon capability to supply the required Quality and at the same time, it ensures that Elcon maintains Quality at an optimal cost. Elcon products satisfy Customers and meet the specifications and rules of international standards. Safety, performance, reliability, product documentation and truth in advertising are the basic principles of product Quality.

**Quality in Services** is a factor of growing importance to achieve market penetration and Elcon considers service as an integral part of the Customer package and checks continuously that its services meet Customer’s requirements.

Constant improvement is the foundation of Total Quality. Elcon continuously ensures that the performance of products, services, management and the Quality System, meet customer requirements. Improvement can only be obtained with the active participation and involvement of all personnel and therefore Elcon management recognises that the human resources of the company play a vital role in the achievement of its objectives.

## 10. WARRANTY

### • **General**

Elcon Instruments certifies that all the instruments of their manufacture are immune from defects or loss of essential quality, and whenever they are apparatus, Elcon also guarantees proper operation. The duration of the warranty period is indicated in the order confirmation and starts from the date of delivery or on site test (if required). Unless otherwise specified the warranty is of 12 months, from delivery date.

The action due to the customer for vices, defects, or loss of quality is subject to the terms of articles 1495,1497 C.C. (Italian Civil Code). The denunciation of the, defect or quality loss must be made by the customer by registered mail, telex, fax, or equivalent written form to be sent to the main office of Elcon Instruments.

### • **Limits - burdens - obligations**

- a) The warranty is limited to repairing and substitution, FOB Elcon Instruments factory, of the useless parts, for a confirmed defect of materials and/or workmanship, free of charge, and the remaining, shipping, dismounting and mounting expenses (operations that in any case must be done in accordance with the supplier), at the customer's charge. In no case Elcon Instruments will be held responsible for expenses, for loss of profit and/or damage, direct or indirect, that can be incurred by the customer due to a fault or defect of the material.
- b) The warranty ends for instruments or materials damaged by:
  - shipment
  - storage non conforming to the instruction manual specifications
  - incorrect installation
  - loss of adequate protection for the type of installation (mechanical, climatic, etc.)
  - incorrect application of power supply voltage
  - erroneous wiring of the power supply line (applied on input or output measuring circuits)
- c) The warranty ends for instruments or materials if repaired, modified, or simply tampered with, even if only in part, by personnel not authorised by Elcon Instruments and also ends if used in improper way and/or not conforming with the given instructions.
- d) The warranty is valid only if payment has been received from the customer in a timely fashion, as per the original agreement; otherwise it is void.
- e) All parts that are subject to normal wear and inevitable deterioration are excluded from this warranty.
- f) In case of having to return the instrument to one of the Elcon Instruments authorised labs for repair, the customer shall obtain a written authorisation with shipping instructions from Elcon Instruments. Shipment expenses, all the concerned burdens, and the risk of loss or damage of the returned instrument are exclusively born by the customer.

The same rules apply also when the instrument needs to be replaced.

- g) During the warranty period, the customer will allow any personnel appointed by Elcon Instruments execute control of the instruments and materials.
- h) The customer cannot require cancellation of the contract in reason of vices or defects, but only their elimination or, when they cannot be repaired, the replacement of the instruments, if available on the market. In case the replacement is for any reason impossible, Elcon Instruments has the faculty to offer instruments of the same or equivalent type, quality and efficiency, suitable to the same use.
 

If the customer refuses such offer without justified motivation he is entitled to reimbursement of the money already paid or a refund of the real incurred expenses.
- i) For items sub-supplied by Elcon Instruments the standard warranty terms as given by the original manufacturer are applicable.
- j) The warranty must be considered for material repaired, substituted on ex works basis.

***Such warranty replaces and supersedes any other declared or implicit warranty***

## 11. ACRONYMS

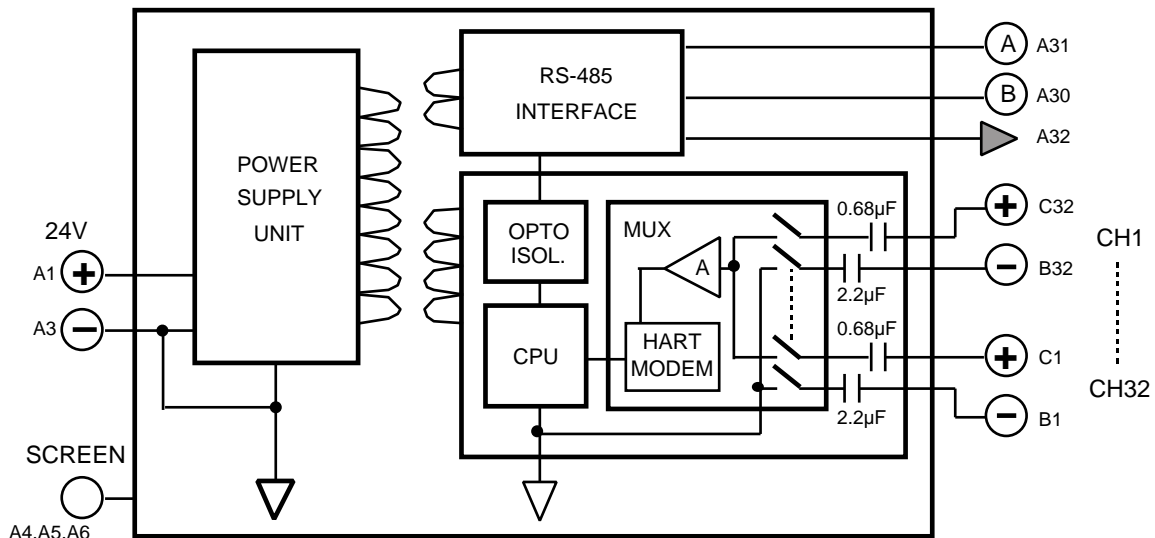
<b>AMS</b>	<i>Asset Management Solutions</i>
<b>DCS</b>	<i>Distributed Control System</i>
<b>FSK</b>	<i>Frequency Shift Keying</i>
<b>HART®</b>	<i>Highway Addressable Remote Transducer</i>
<b>HHC</b>	<i>Hard Held Communication</i>
<b>HIS</b>	<i>Elcon HART Interface Solutions</i>
<b>HSM</b>	<i>HART Signal Multiplexer</i>
<b>IAC</b>	<i>Elcon patented Interface Adapter Card</i>
<b>IS</b>	<i>Intrinsic Safety</i>
<b>MM</b>	<i>Multiplexer Module</i>
<b>MW</b>	<i>Maintenance Workstation</i>
<b>PCC</b>	<i>Process Control Unit</i>
<b>PLC</b>	<i>Programmable Logic Controller</i>
<b>SCADA</b>	<i>Supervisory Control and Data Acquisition</i>
<b>SSMS</b>	<i>Smart Signal Multiplexer System</i>
<b>ST</b>	<i>Smart Transmitter</i>
<b>TB</b>	<i>Termination Board</i>

- **Cornerstone is a trademark of Applied System Technologies, Inc.**
- **HART is a registered trademark of Rosemount Inc.**
- **Windows is a trademark of Microsoft Corporation.**
- **AMS Asset Management Solutions is a trademark of Fisher Rosemount.**

## 12. APPENDIX A: MUX2700G ISOLATION STRUCTURE

### 12.1 Three-port isolation

The three-port isolation structure of the Mux2700G is depicted in Fig.8. As you can see, both the 24V supply input and the RS-485 serial interface are isolated from the HART section, that is to say, from the HART signals on the field devices. This is full galvanic isolation, implemented either by transformer or by optocoupler.



**Fig. 8**  
*Mux2700G ISOLATION STRUCTURE*

The galvanic isolation specifications for the Mux2700G are summarised in the following table:

24V supply	→	Field channels	1400 Vac, rms
24V supply	→	RS-485 serial port	1400 Vac, rms
RS-485 serial port	→	Field channels	500 Vac, rms

#### *Mux2700G GALVANIC ISOLATION SPECIFICATIONS*

### 12.2 Input-channels isolation

When you look at the field channels, you can see that full galvanic isolation is not implemented. Instead, a series of non-polarised capacitors are inserted on each external interface line. The purpose of these capacitors is to block the DC signal component present on each 4-20mA external loop, avoiding both a DC error induced on the loop and any undesirable ground-loop.

The presence of a non-polarised capacitor in series with both the + and the - terminal of each channel is very convenient for a variety of reasons, as summarised in the following:

- It is possible to sense the HART signal at different DC voltage levels on each channel, as often required when the same MUX interfaces both Transmitters and I/P devices or in other "mixed" configurations.
- It is not mandatory, to connected the + MUX terminal to the + side of the 4-20 mA current loop (in fact, the MUX input terminals are basically not polarised).

- As better explained in section 12.4, the MUX can tolerate one or more short-failed input capacitors while still working properly, the probability of loop interference is also very low for a wide range of internal MUX faults.

The MUX input isolation was designed to allow the highest flexibility in connecting the channels to sense the HART signal. The max 30 Vdc input voltage (specified between all terminals, both belonging to the same channel or not) makes it possible to connect any MUX terminal to whatever voltage level can be derived from a 24 Vdc supply, +20% tolerance included.

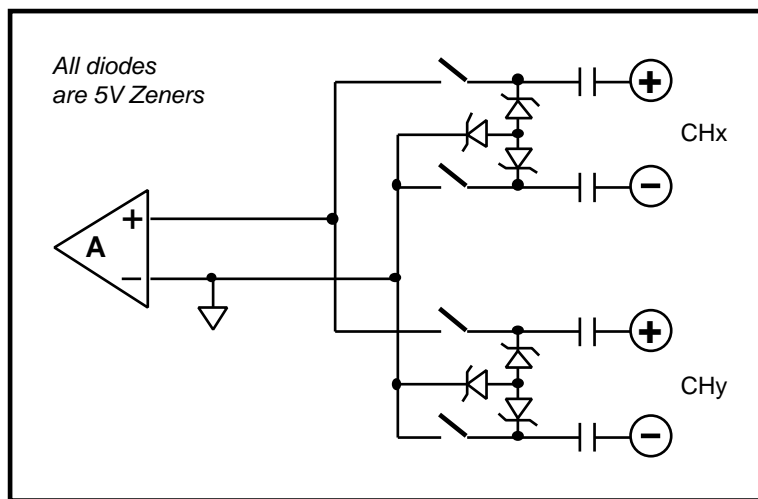
The input-channels isolation specifications for the Mux2700G are summarised in the following table:

Channel number:	32 signal loops (64 terminals)
Channel isolation technique:	capacitor isolation, 2 capacitors for each loop
+ terminal capacitor:	0.68 $\mu$ F, 63V polyester capacitor (non-polarised)
- terminal capacitor:	2.2 $\mu$ F, 50V non-polarised electrolytic capacitor
Allowed common mode voltage:	up to 30V
Max input common-mode voltage: (between terminals of different channels)	30 Vdc
Max input differential-mode voltage: (between terminals of the same channel)	30 Vdc
Common mode internal clamping: (between terminals of different channels)	+/- 10V (for transient or AC signals)
Differential mode internal clamping: (between terminals of the same channel)	+/- 5V (for transient or AC signals)

*Mux2700G INPUT ISOLATION SPECIFICATIONS*

To avoid any possible damage to the sensitive input circuitry, an internal, zener-diode based clamping network (Fig. 9) was inserted that operates both on common-mode and on differential-mode transients. This is required because, for relevant input transient or AC signals, the input capacitors could momentarily couple to the input circuitry with a voltage level higher than the allowed voltage rating (i.e., +/- 5V).

Typically, the clamping network needs only to operate at the MUX unit during plug-in time, when the input capacitors are initially charged. During the capacitors charge time (typically less than 1 ms) the input circuit does in fact sink a some DC current from the loop, but the induced error on the 4-20 mA signal is so short in time that it is rarely detected in any situation.



**FIG. 9**  
*Mux2700G INPUT CLAMPING NETWORK*

### 12.3 Galvanic versus capacitive isolation

Having understood the advantages of a full, non-polarised capacitor-based isolation, you must however be aware that this is not the same as a full galvanic isolation implemented on each channel, which was avoided on the MUX design due to space constraints and higher manufacturing costs.

In the following, we will try to outline the main differences between the Galvanic and the Capacitive isolation techniques:

- Full, galvanic isolation is associated with clearly specified, solid isolation distances, with reference to the applicable standards. For space reasons, the selected Mux2700G capacitors are not generally compliant with this requirement.
- Full, galvanic isolation is generally requested to withstand a test voltage starting from 500 Vdc up, while the Mux 2700G capacitor rating is around 60 Vdc only.
- Full, galvanic isolation is generally specified with the lowest possible stray capacitance. For functional reasons (that is to say, to enable the HART frequency acquisition) the Mux2700G capacitors are much higher of what is usually found in a galvanic isolated solution.

Due to the previous considerations, when you connect a MUX2700G to 4-20mA loops that are galvanic isolated from each other, you lose the full galvanic isolation among the channels. On the other hand, you still have a relevant advantage with respect to a solution that simply connects the channels with a common point, because you still have full DC isolation up to the specified voltage and you don't need to worry about possible ground-loop induced errors on the 4-20mA signals.

### 12.4 Safety-related issues

It is important to stress the fact that capacitor-based isolation is not equivalent to a full galvanic isolation, however this does not mean that the Mux2700G can be expected, under reasonable fault conditions, to interfere with the connected 4-20 mA loops. A few application examples can in fact be useful to clarify the situation.

- **Galvanic isolated field loops**

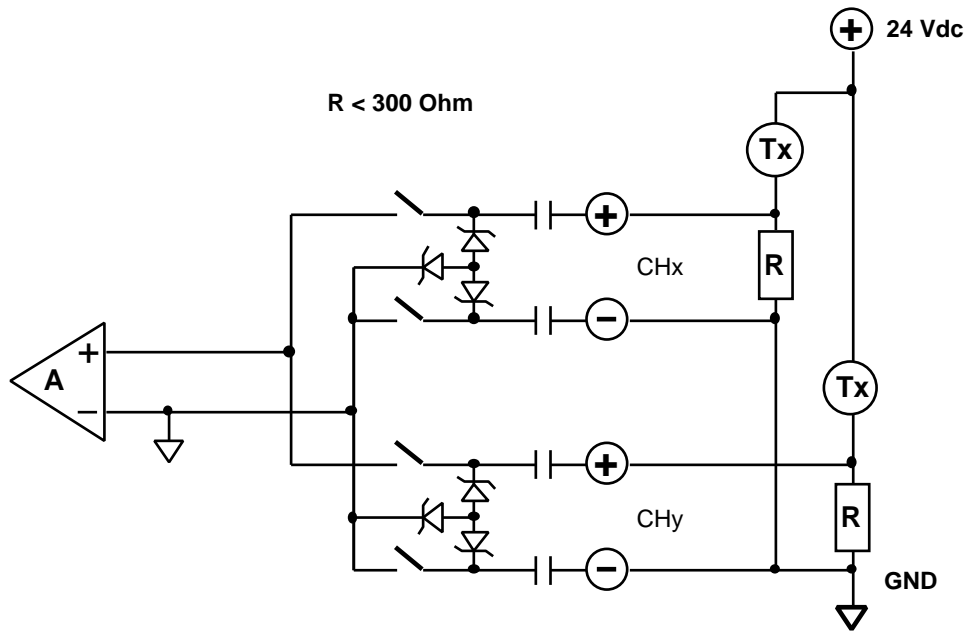
Let us assume that you connect with 4-20mA loops that are fully galvanic isolated from each other. In this case, it can be shown that a single shorted input capacitor on each channel, plus any possible additional MUX fault (apart from shorted input capacitors) does never result in any interference on the 4-20mA loops. In addition, with a single shorted capacitor on each channel the MUX is still fully functional.

In a more formal term, the probability of any "electrical feedback" of the Mux2700G on the loops signals is very low, and you can consider the control system for "fail-safe" applications (this doesn't mean, however, that the MUX is fail-safe certified or that it will keep working properly when in a generic "single-fault" condition).

- **Common-point field loops**

A similar situation can be found when the 4-20mA loops which the Mux2700G connects to share a common Vdc connection point, with a current sense resistor < 300 Ohm to GND (Fig. 10).

As before, it can in fact be shown that a single shorted capacitor on each channel, plus any possible additional MUX fault (apart from shorted input capacitors) does never result in any interference on the 4/20 mA loops. In addition, with a single shorted capacitor on each channel the MUX is still fully functional.



**Fig. 10**

*COMMON-POINT FIELD LOOPS CONFIGURATION*

As a final remark, we can observe that, whatever is the field-loops isolation or connection, a single capacitor fault plus any other possible additional fault within the Mux2700G never results in any errors induced from the Mux2700G on any 4-20mA loop.

## 12.5 Conclusions

By this note, it was possible to clarify how the Mux2700G isolation structure is such to guarantee both an high level of application flexibility and a good reliability and fault tolerance (as for induced errors).

The presence of two series capacitors on each 4-20mA loop was discussed and the advantages of the solution explained.

Some safety related issues were finally discussed, showing that, with a minimum of application-related analysis, the Mux2700G can be designed so to minimise the probability of any electrical feedback on the connected 4-20mA loops.